

ON THE BUREAU REPRESENTATION FOR $n = 4$

Anzor Beridze and Paweł Traczyk

Batumi Shota Rustaveli State University

a.beridze@bsu.edu.ge

Institute of Mathematics of University of Warsaw

traczyk@mimuw.edu.pl

Department of Mathematics of

Batumi, Georgia

July 7, 2019

Abstract

The problem of faithfulness of the (reduced) Burau representation for $n = 4$ is known to be equivalent to the problem of whether certain two matrices A and B generate a free group of rank two [Bir]. In [Ber-Tra1] we gave a simple proof that $\langle A^3, B^3 \rangle$ is a free group of rank two, the result known earlier from [Wit-Zar]. In this paper we use a combination of methods of linear algebra and homology theory (the forks and noodles approach) [Ber-Tra2], [Big] to give another proof that $\langle A^3, B^3 \rangle$ is a free group and some explanations which show why we believe that $\langle A^2, B^2 \rangle$ should be a free group as well.

1 2 3 4 5

¹[Ber-Tra1] Beridze, A.; Traczyk, P. Burau representation for $n = 4$. *J. Knot Theory Ramifications* 27 (2018), no. 3, 1840002, 6 pp.

²[Ber-Tra2] Beridze, A.; Traczyk, P. Forks, noodles and the Burau representation for $n = 4$. *Trans. A. Razmadze Math. Inst.* 172 (2018), no. 3, part A, 337–353.

³[Bir] Joan S Birman. Braids, links, and mapping class groups. *Annals of Mathematics Studies, No. 82, Princeton University Press, Princeton, NJ (1974)*

⁴[Big] Stephen Bigelow. The Burau representation is not faithful for $n = 5$. *Geom. Topol.* 3 (1999), 397–404

⁵[Wit-Zar] S. Witzel and M. C. B. Zaremsky. A free subgroup in the image of the

The Burau Representation, Noodles and Forks

The reduced Burau representation for $n = 4$ is the homomorphism

$$\rho : B_4 \rightarrow \text{Aut} \left(H_1 \left(\tilde{D}_4; Z \right) \right) \quad (1)$$


which is defined by

$$\rho(\sigma) = \tilde{\varphi}_*, \quad \forall \sigma \in B_4, \quad (2)$$

where $\varphi : D_4 \rightarrow D_4$ is a transformation which is representative of the element $\sigma \in B_4$. The group $H_1(\tilde{D}_4; Z)$ is a free $Z[t, t^{-1}]$ -module of rank 3 [Lon-Pat], [Big], [Ber-Tra2].

⁶[Lon-Pat] D. D. Long and M. Paton. The Burau representation is not faithful for $n \geq 6$. *Topology* **32** (1993), no. 2, 439—447

⁷[Big] Stephen Bigelow. The Burau representation is not faithful for $n = 5$. *Geom. Topol.* **3** (1999), 397-404

⁸[Ber-Tra.2] Beridze, A.; Traczyk, P. Forks, noodles and the Burau representation for $n = 4$. *Trans. A. Razmadze Math. Inst.* **172** (2018), no. 3, part A, 337-353. 

The Burau Representation, Noodles and Forks

The reduced Burau representation for $n = 4$ is the homomorphism

$$\rho : B_4 \rightarrow \text{Aut} \left(H_1 \left(\tilde{D}_4; Z \right) \right) \quad (1)$$

which is defined by

$$\rho(\sigma) = \tilde{\varphi}_*, \quad \forall \sigma \in B_4, \quad (2)$$

where $\varphi : D_4 \rightarrow D_4$ is a transformation which is representative of the element $\sigma \in B_4$. The group $H_1(\tilde{D}_4; Z)$ is a free $Z[t, t^{-1}]$ -module of rank 3 [Lon-Pat], [Big], [Ber-Tra2]. On the other hand $H_1(\tilde{D}_4; \mathbb{Z})$ is a free $\mathbb{Z}[t, t^{-1}]$ -module of rank 3 and if we take a basis of it, then $\text{Aut} \left(H_1 \left(\tilde{D}_4; \mathbb{Z} \right) \right)$ can be identified with $GL(3, \mathbb{Z}[t, t^{-1}])$.

6 7 8

⁶[Lon-Pat] D. D. Long and M. Paton. The Burau representation is not faithful for $n \geq 6$. *Topology* **32** (1993), no. 2, 439–447

⁷[Big] Stephen Bigelow. The Burau representation is not faithful for $n = 5$. *Geom. Topol.* **3** (1999), 397–404

⁸[Ber-Tra.2] Beridze, A.; Traczyk, P. Forks, noodles and the Burau representation for $n = 4$. *Trans. A. Razmadze Math. Inst.* **172** (2018), no. 3, part A, 337–353.

The basis of the $\mathbb{Z}[t, t^{-1}]$ -module $H_1(\tilde{D}_4; \mathbb{Z})$

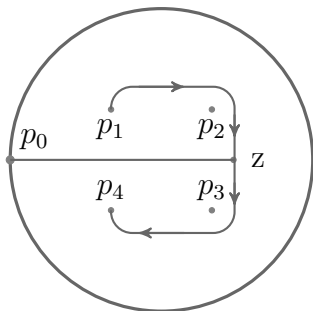
Definition

A fork is an embedded oriented tree F in the disc D with four vertices p_0, p_i, p_j and z , where $i \neq j, i, j \in \{1, 2, 3, 4\}$ such that (see [3]):

- 1 F meets the puncture points only at p_i and p_j ;
- 2 F meets the boundary ∂D_4 only at p_0 ;
- 3 All three edges of F have z as a common vertex.

The basis of the $\mathbb{Z}[t, t^{-1}]$ -module $H_1(\tilde{D}_4; \mathbb{Z})$

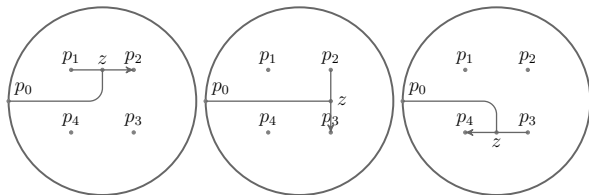
The edge of F which contains p_0 is called the **handle**. The union of the other two edges is denoted by $T(F)$ and it is called **tine of F** . Orient $T(F)$ so that the handle of F lies to the right of $T(F)$ [Big].



The basis of the $\mathbb{Z}[t, t^{-1}]$ -module $H_1(\tilde{D}_4; \mathbb{Z})$

A Standard Fork

A standard fork F_i , $i = 1, 2, 3$ is the fork whose tine edge is the straight arc connecting the i -th and the $(i+1)$ -st punctured points and whose handle has the form as in Figure below.

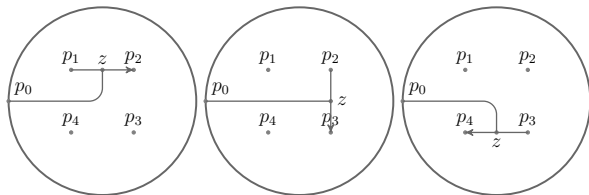


¹¹[Big] Stephen Bigelow. The Burau representation is not faithful for $n = 5$.

The basis of the $\mathbb{Z}[t, t^{-1}]$ -module $H_1(\tilde{D}_4; \mathbb{Z})$

A Standard Fork

A standard fork F_i , $i = 1, 2, 3$ is the fork whose tine edge is the straight arc connecting the i -th and the $(i+1)$ -st punctured points and whose handle has the form as in Figure below.



It is known that if F_1 , F_2 and F_3 are the corresponding homology classes, then they form a basis of $H_1(\tilde{D}_4; \mathbb{Z})$ [Big].

11

¹¹[Big] Stephen Bigelow. The Burau representation is not faithful for $n = 5$.

The basis of the $\mathbb{Z}[t, t^{-1}]$ -module $H_1(\tilde{D}_4; \mathbb{Z})$

Using the basis derived from F_1, F_2, F_3 , any automorphism

$$\tilde{\varphi}_* : H_1(\tilde{D}_4; \mathbb{Z}) \rightarrow H_1(\tilde{D}_4; \mathbb{Z})$$

can be viewed as a 3×3 matrix with entries in the ring $\mathbb{Z}[t, t^{-1}]$ [Big]. If $\varphi : D_4 \rightarrow D_4$ is representing an element $\sigma \in B_4$, then we need to write the matrix $\rho(\sigma) = \tilde{\varphi}_*$ in terms of homology (algebraic) intersection pairing

$$\langle -, - \rangle : H_1(\tilde{D}_4, \partial\tilde{D}_4; \mathbb{Z}) \times H_1(\tilde{D}_4; \mathbb{Z}) \rightarrow \mathbb{Z}[t, t^{-1}].$$

¹²[Big] Stephen Bigelow. The Burau representation is not faithful for $n = 5$.

Geom. Topol. 3 (1999), 397-404

The basis of the $\mathbb{Z}[t, t^{-1}]$ -module $H_1(\tilde{D}_4; \mathbb{Z})$

Using the basis derived from F_1, F_2, F_3 , any automorphism

$$\tilde{\varphi}_* : H_1(\tilde{D}_4; \mathbb{Z}) \rightarrow H_1(\tilde{D}_4; \mathbb{Z})$$

can be viewed as a 3×3 matrix with entries in the ring $\mathbb{Z}[t, t^{-1}]$ [Big]. If $\varphi : D_4 \rightarrow D_4$ is representing an element $\sigma \in B_4$, then we need to write the matrix $\rho(\sigma) = \tilde{\varphi}_*$ in terms of homology (algebraic) intersection pairing

$$\langle -, - \rangle : H_1(\tilde{D}_4, \partial\tilde{D}_4; \mathbb{Z}) \times H_1(\tilde{D}_4; \mathbb{Z}) \rightarrow \mathbb{Z}[t, t^{-1}].$$

For this aim we need to define the noodles which represent relative homology classes in $H_1(\tilde{D}_4, \partial\tilde{D}_4; \mathbb{Z})$.

12

¹²[Big] Stephen Bigelow. The Burau representation is not faithful for $n = 5$.

Geom. Topol. 3 (1999), 397-404

The basis of the $\mathbb{Z}[t, t^{-1}]$ -module $H_1(\tilde{D}_4, \partial\tilde{D}_4; \mathbb{Z})$

Definition

A noodle is an embedded oriented arc in D_4 , which begins at the base point p_0 and ends at some point of the boundary ∂D_4 [Big].

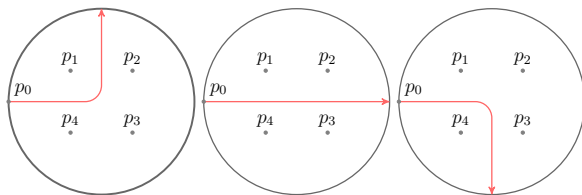
¹³[Big] Stephen Bigelow. The Burau representation is not faithful for $n = 5$.

Geom. Topol. 3 (1999), 397-404

The basis of the $\mathbb{Z}[t, t^{-1}]$ -module $H_1(\tilde{D}_4, \partial\tilde{D}_4; \mathbb{Z})$

Definition

A noodle is an embedded oriented arc in D_4 , which begins at the base point p_0 and ends at some point of the boundary ∂D_4 [Big].



Standard noodles: N_1, N_2, N_3

The Noodle-Fors Pairing

For each $b \in H_1(\tilde{D}_4, \partial\tilde{D}_4; \mathbb{Z})$ and $a \in H_1(\tilde{D}_4; \mathbb{Z})$ we should take the corresponding fork N and noodle F and define the polynomial $\langle N, F \rangle \in \mathbb{Z}[t, t^{-1}]$. It does not depend on the choice of representatives of homology classes and so

$$\langle -, - \rangle : H_1(\tilde{D}_4, \partial\tilde{D}_4; \mathbb{Z}) \times H_1(\tilde{D}_4; \mathbb{Z}) \rightarrow \mathbb{Z}[t, t^{-1}]$$

is well-defined [Big].

¹⁴[Big] Stephen Bigelow. The Burau representation is not faithful for $n = 5$.

Geom. Topol. 3 (1999), 397-404

The Noodle-Fork Pairing

For each $b \in H_1(\tilde{D}_4, \partial\tilde{D}_4; \mathbb{Z})$ and $a \in H_1(\tilde{D}_4; \mathbb{Z})$ we should take the corresponding fork N and noodle F and define the polynomial $\langle N, F \rangle \in \mathbb{Z}[t, t^{-1}]$. It does not depend on the choice of representatives of homology classes and so

$$\langle -, - \rangle : H_1(\tilde{D}_4, \partial\tilde{D}_4; \mathbb{Z}) \times H_1(\tilde{D}_4; \mathbb{Z}) \rightarrow \mathbb{Z}[t, t^{-1}]$$

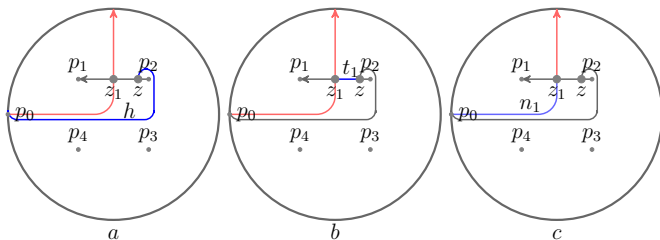
is well-defined [Big].

The map defined by the above formula is called **the noodle–fork pairing**.¹⁴

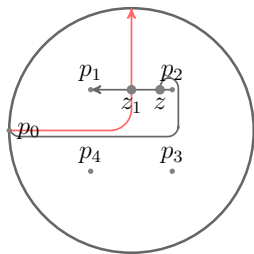
¹⁴[Big] Stephen Bigelow. The Burau representation is not faithful for $n = 5$.
Geom. Topol. 3 (1999), 397–404

Geometric computation of noodle-forks pairing

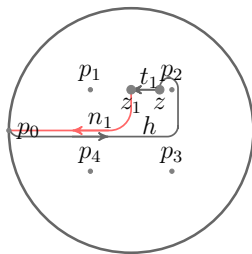
Let z_1, z_2, \dots, z_n be the transversal intersection of N and F , ε_i be the sign of the intersection between $T(F)$ and N at z_i and $e_i = [\gamma_i]$ be the winding number of the loop γ_i around the puncture points p_1, p_2, p_3, p_4 , where γ_i is the composition of three paths h, t_i and n_i : 1) h is a path from p_0 to z along the handle of F (see Figure a); 2) t_i is a path from z to z_i along the tine $T(F)$ (see Figure b); 3) n_i is a path from z_i to p_0 along the noodle N (see Figure c):



Images of the Generators $\sigma_1, \sigma_2, \sigma_3$ of the 4-Braid group B_4



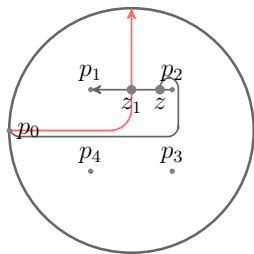
$$a : \varepsilon_1 = -1$$



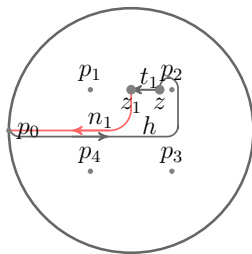
$$b : \gamma_1 = n_1 * t_1 * h; \varepsilon_1 = 1$$

The intersection of the tine $T(F_1\sigma_1)$ of the fork $F_1\sigma_1$ and the noodle N_1 at point z_1 is negative which means that $\varepsilon_i = -1$ (see Figure a).

Images of the Generators $\sigma_1, \sigma_2, \sigma_3$ of the 4-Braid group B_4



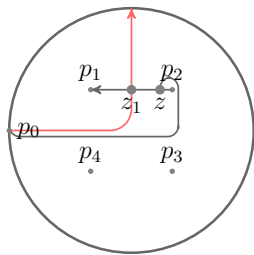
$$a : e_1 = -1$$



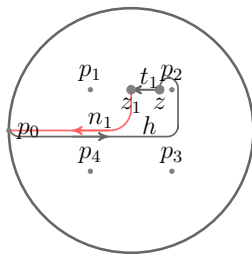
$$b : \gamma_1 = n_1 * t_1 * h; \varepsilon_1 = 1$$

The intersection of the tine $T(F_1\sigma_1)$ of the fork $F_1\sigma_1$ and the noodle N_1 at point z_1 is negative which means that $\varepsilon_i = -1$ (see Figure a). The winding number e_1 of the loop γ_1 (see Figure b) around puncture points equals 1.

Images of the Generators $\sigma_1, \sigma_2, \sigma_3$ of the 4-Braid group B_4



$$a : e_1 = -1$$



$$b : \gamma_1 = n_1 * t_1 * h; \varepsilon_1 = 1$$

The intersection of the tine $T(F_1\sigma_1)$ of the fork $F_1\sigma_1$ and the noodle N_1 at point z_1 is negative which means that $\varepsilon_i = -1$ (see Figure a). The winding number e_1 of the loop γ_1 (see Figure b) around puncture points equals 1. Therefore

$$\rho_{11}(\sigma_1) = \langle N_1, F_1\sigma_1 \rangle = -t$$

Geometric colulation of $\rho_{ij}(\sigma)$

Lemma

Let $\sigma \in B_n$. Then for $1 \leq i, j \leq n - 1$, the entry $\rho_{ij}(\sigma)$ of its Burau matrix $\rho(\sigma)$ is given by

$$\rho_{ij}(\sigma) = \langle N_i, F_j \sigma \rangle.$$

15 16

¹⁵[Big] Stephen Bigelow. The Burau representation is not faithful for $n = 5$. *Geom. Topol.* 3 (1999), 397-404

¹⁶[Mat-Ito] Matthieu Calvez and Tetsuya Ito. Garside-theoretic analysis of Burau representations. *arXiv:1401.2677v2*

Geometric colulation of $\rho_{11}(\sigma_1)$

Under the convention adopted we have:

$$\rho(\sigma_1) = \begin{pmatrix} -t & t & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \rho(\sigma_2) = \begin{pmatrix} 1 & 0 & 0 \\ 1 & -t & t \\ 0 & 0 & 1 \end{pmatrix}$$

and

$$\rho(\sigma_3) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & -t \end{pmatrix}.$$

17 18

¹⁷[Ber-Tra.2] Beridze, A.; Traczyk, P. Forks, noodles and the Burau representation for $n = 4$. *Trans. A. Razmadze Math. Inst.* 172 (2018), no. 3, part A, 337–353.

¹⁸[Dav] L. Davitadze, Braid groups and Burau representation. *Bachelor thesis, Batumi, 2019*

The Bokut-Vesnin generators and kernel elements of the Burau representation

Let $\varphi : B_4 \rightarrow B_3$ be the homomorphism defined by

$$\varphi(\sigma_1) = \sigma_1, \quad \varphi(\sigma_2) = \sigma_2, \quad \varphi(\sigma_3) = \sigma_1.$$

The kernel of φ is known to be a free group $F(a, b)$ of two generators [Bok-Ves];

$$a = \sigma_1 \sigma_2 \sigma_3^{-1} \sigma_1 \sigma_2^{-1} \sigma_1^{-1}, \quad b = \sigma_3 \sigma_1^{-1}.$$

¹⁹[Bok-Ves] Bokut, Leonid; Vesnin, Andrei. Gröbner-Shirshov bases for some braid groups. *J. Symbolic Comput.* 41 (2006), no. 3-4, 357-371.

The Bokut-Vesnin generators and kernel elements of the Burau representation

Let $\varphi : B_4 \rightarrow B_3$ be the homomorphism defined by

$$\varphi(\sigma_1) = \sigma_1, \quad \varphi(\sigma_2) = \sigma_2, \quad \varphi(\sigma_3) = \sigma_1.$$

The kernel of φ is known to be a free group $F(a, b)$ of two generators [Bok-Ves];

$$a = \sigma_1 \sigma_2 \sigma_3^{-1} \sigma_1 \sigma_2^{-1} \sigma_1^{-1}, \quad b = \sigma_3 \sigma_1^{-1}.$$

This was proved by L. Bokut and A. Vesnin [Bok-Vis].


19

¹⁹[Bok-Ves] Bokut, Leonid; Vesnin, Andrei. Gröbner-Shirshov bases for some braid groups. *J. Symbolic Comput.* 41 (2006), no. 3-4, 357-371.

The Bokut-Vesnin generators and kernel elements of the Burau representation

We will refer to a and b as the Bokut–Vesnin generators:

$$a = \sigma_1 \sigma_2 \sigma_3^{-1} \sigma_1 \sigma_2^{-1} \sigma_1^{-1}, \quad b = \sigma_3 \sigma_1^{-1}.$$

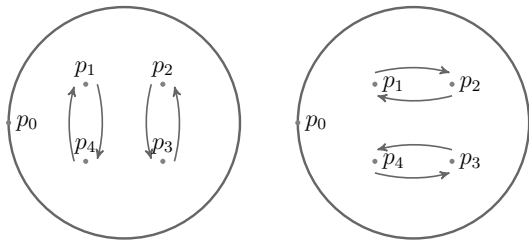
²⁰[Ber-Tra.2] Beridze, A.; Traczyk, P. Forks, noodles and the Burau representation for $n = 4$. *Trans. A. Razmadze Math. Inst.* 172 (2018), no. 3, part A, 337–353. 

The Bokut-Vesnin generators and kernel elements of the Burau representation

We will refer to a and b as the Bokut–Vesnin generators:

$$a = \sigma_1 \sigma_2 \sigma_3^{-1} \sigma_1 \sigma_2^{-1} \sigma_1^{-1}, \quad b = \sigma_3 \sigma_1^{-1}.$$

The generators a and b are in fact much more similar than they look at the first glance:



The Bokut-Vesnina generators and kernel elements of the Burau representation

Proposition

The kernel $\ker \rho_4$ of the Burau representation map

$$\rho_4 : B_4 \rightarrow GL(3, \mathbb{Z}[t, t^{-1}])$$

is a subgroup of the kernel $\ker \varphi$ of the map $\varphi : B_4 \rightarrow B_3$, defined above by

$$\varphi(\sigma_1) = \sigma_1, \quad \varphi(\sigma_2) = \sigma_2, \quad \varphi(\sigma_3) = \sigma_1.$$

Therefore

$$\ker \rho_4 \subset \ker \varphi$$

The Bokut-Vesnin generators and kernel elements of the Burau representation

Proof. Let us make a slight detour into the realm of the Temperley-Lieb algebras TL_3 and TL_4 . The Temperley-Lieb algebra TL_n is defined as an algebra over $\mathbb{Z}[t, t^{-1}]$. It has $n - 1$ generators $\{U_i^i\}_{i=1}^{n-1}$, and the following relations:

$$(TL1) \quad U_i^i U_i^i = (-t^{-2} - t^2) U_i^i,$$

$$(TL2) \quad U_i^i U_j^j U_i^i = U_i^i, \text{ for } |i - j| = 1,$$

$$(TL3) \quad U_i^i U_j^j = U_j^j U_i^i, \text{ for } |i - j| > 1.$$

The Bokut-Vesnina generators and kernel elements of the Burau representation

Proof. Let us make a slight detour into the realm of the Temperley-Lieb algebras TL_3 and TL_4 . The Temperley-Lieb algebra TL_n is defined as an algebra over $\mathbb{Z}[t, t^{-1}]$. It has $n - 1$ generators $\{U_i^i\}_{i=1}^{n-1}$, and the following relations:

$$(TL1) \quad U_i^i U_i^i = (-t^{-2} - t^2) U_i^i,$$

$$(TL2) \quad U_i^i U_j^j U_i^i = U_i^i, \text{ for } |i - j| = 1,$$

$$(TL3) \quad U_i^i U_j^j = U_j^j U_i^i, \text{ for } |i - j| > 1.$$

The Bokut-Vesnin generators and kernel elements of the Burau representation

Let us consider the homomorphism $\psi : TL_4 \rightarrow TL_3$ defined by

$$U_1^1 \rightarrow U_1^1, U_2^2 \rightarrow U_2^2, U_3^3 \rightarrow U_1^1.$$

Let $\theta : B_n \rightarrow TL_n$ be the Jones' representation defined by sending σ_i to $A + A^{-1}U_i^i$. It is known (see [Big.2], Proposition 1.5) that for $n = 3, 4$ we have $\ker \theta_n = \ker \rho_n$. Moreover, the following diagram is obviously commutative:

$$\begin{array}{ccc} B_4 & \xrightarrow{\theta_4} & TL_4 \\ \varphi \downarrow & & \downarrow \psi \\ B_3 & \xrightarrow{\theta_3} & TL_3 \end{array}$$

²¹[Big.2] Stephen Bigelow. Does the Jones polynomial detect the unknot? *J. Knot Theory and Ramifications* (4) 11 (2002), 493-505

The Bokut-Vesnin generators and kernel elements of the Burau representation

Let us consider the homomorphism $\psi : TL_4 \rightarrow TL_3$ defined by

$$U_1^1 \rightarrow U_1^1, U_2^2 \rightarrow U_2^2, U_3^3 \rightarrow U_1^1.$$

Let $\theta : B_n \rightarrow TL_n$ be the Jones' representation defined by sending σ_i to $A + A^{-1}U_i^i$. It is known (see [Big.2], Proposition 1.5) that for $n = 3, 4$ we have $\ker \theta_n = \ker \rho_n$. Moreover, the following diagram is obviously commutative:

$$\begin{array}{ccc} B_4 & \xrightarrow{\theta_4} & TL_4 \\ \varphi \downarrow & & \downarrow \psi \\ B_3 & \xrightarrow{\theta_3} & TL_3 \end{array}$$

The representation θ_3 is faithful and therefore $\ker \rho_4 = \ker \theta_4 \subset \ker \varphi$.

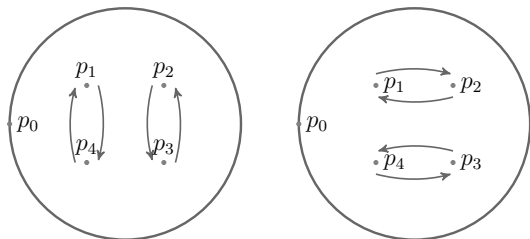
²¹

[Big.2] Stephen Bigelow. Does the Jones polynomial detect the unknot? *J. Knot Theory and Ramifications* (4) 11 (2002), 493-505

Images of The Bokut-Vesnin generators

Under the convention adopted we have:

$$A = \rho(a) = \begin{pmatrix} -t+1 & 0 & -1 \\ -t+t & -t & 0 \\ -t & 0 & 0 \end{pmatrix}, \quad B = \rho(b) = \begin{pmatrix} -t^{-1} & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & -t \end{pmatrix}$$



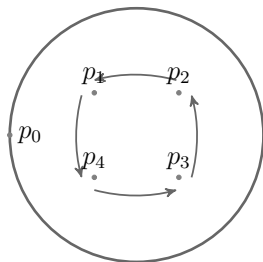
22 23

²²[Ber-Tra.3] Beridze, A.; Traczyk, P. On the Burau representation for $n = 4$.
arXiv:1904.11730

²³[Dav] L. Davitadze, Braid groups and Burau representation. *Bachelor thesis, Batumi, 2019*

Turning the punctured disk D_4 by ninety degrees

Let t be a transformation of D_4 , which has the following form:



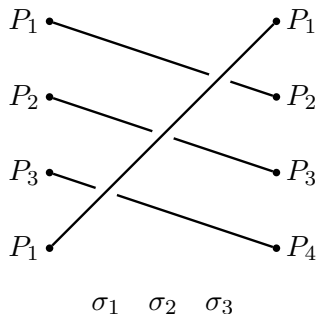
24 25

²⁴[Ber-Tra.3] Beridze, A.; Traczyk, P. On the Burau representation for $n = 4$.
arXiv:1904.11730

²⁵[Dav] L. Davitaddze, Braid groups and Burau representation. *Bachelor thesis, Batumi, 2019*

Turning the punctured disk D_4 by ninety degrees

Therefore, t is resantatiove of the braid is $\sigma_1\sigma_2\sigma_3$:



26 27

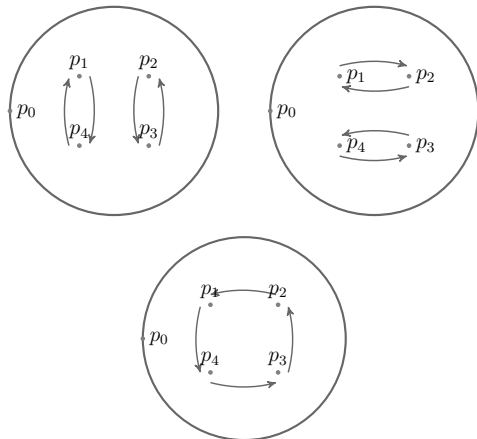
²⁶[Ber-Tra.3] Beridze, A.; Traczyk, P. On the Burau representation for $n = 4$.
arXiv:1904.11730

²⁷[Dav] L. Davitaddze, Braid groups and Burau representation. *Bachelor thesis, Batumi, 2019*

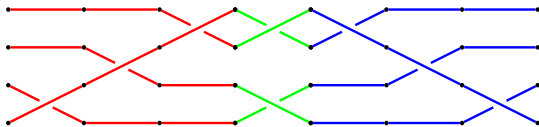
Conjugating a , a^{-1} and b^{-1} to b

It is easy to check that the following conditions are satisfied:

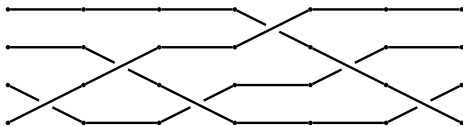
$$a = t^{-1}bt, \quad a^{-1} = tbt^{-1}, \quad b^{-1} = t^2bt^2.$$



Conjugating a^{-1} to b



$$tbt^{-1} = \sigma_1\sigma_2\sigma_3\sigma_1^{-1}\sigma_3\sigma_3^{-1}\sigma_2^{-1}\sigma_1^{-1}$$



$$a^{-1} = \sigma_1\sigma_2\sigma_1^{-1}\sigma_3\sigma_2^{-1}\sigma_1^{-1}$$

Lemma

There exists a matrix T which satisfies the following equality:

$$A = TBT^{-1}, \quad A^{-1} = T^{-1}BT, \quad B^{-1} = T^2BT^2. \quad (3)$$

The considered matrix T is of order four as an element of the group $GL(3, \mathbb{Z}[t, t^{-1}])$.

Conjugating A , A^{-1} and B^{-1} to B

Proof the matrices A , B , A^{-1} and B^{-1} have the same eigenvalues $-t^{-1}$, $-t$ and 1. Therefore, they are conjugate to the same diagonal matrix:

$$\Delta = \begin{bmatrix} -t^{-1} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -t \end{bmatrix}.$$

Conjugating A , A^{-1} and B^{-1} to B

Proof the matrices A , B , A^{-1} and B^{-1} have the same eigenvalues $-t^{-1}$, $-t$ and 1. Therefore, they are conjugate to the same diagonal matrix:

$$\Delta = \begin{bmatrix} -t^{-1} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -t \end{bmatrix}.$$

Let us consider transformation matrices T_A and T_B

$$T_A = \begin{bmatrix} -1 & t^{-1} & 0 \\ -1 & t^{-1} - 1 & 1 \\ -1 & -1 & 0 \end{bmatrix}, \quad T_B = \begin{bmatrix} 1 & 1 & 0 \\ 0 & t^{-1} + 1 & 0 \\ 0 & t^{-1} & 1 \end{bmatrix}.$$

Therefore, the following equalities hold:

$$A = T_A \Delta T_A^{-1}, \quad B = T_B \Delta T_B^{-1}.$$

Hence, we obtain that

$$A = T_A T_B^{-1} B T_B T_A^{-1}.$$

conjugating a , a^{-1} and b^{-1} to b

Let $T = T_A T_B^{-1}$, then we have:

$$T = \rho(t) = \begin{bmatrix} -1 & 1 & 0 \\ -1 & 0 & 1 \\ -1 & 0 & 0 \end{bmatrix}.$$

conjugating a , a^{-1} and b^{-1} to b

Let $T = T_A T_B^{-1}$, then we have:

$$T = \rho(t) = \begin{bmatrix} -1 & 1 & 0 \\ -1 & 0 & 1 \\ -1 & 0 & 0 \end{bmatrix}.$$

On the other hand, direct calculation shows that


$$T^4 = \mathbf{1}, \quad A = T^{-1}BT, \quad A^{-1} = TBT^{-1}, \quad B^{-1} = T^2BT^2.$$

Corollary

Let w be a formally irreducible non-empty word in letters A, B, A^{-1} and B^{-1} with suffix $B^i, i \geq 1$. Then the corresponding product of matrices A, B, A^{-1} and B^{-1} may be written in the form

$$T^{m_{k+1}} B^{n_{k+1}} T^{m_k} B^{n_k} \dots T^{m_2} B^{n_2} T^{m_1} B^{n_1} \quad n_i \in N, \quad m_i \in \{-1, 1\}, \\ m_{k+1} \in \{-1, 0, 1, 2\}.$$

s -pattern: This means a one column matrix in which the position of entries with minimum degree (in the first column of the considered matrix) are checked.

³¹[Ber-Tra.1] Beridze, A.; Traczyk, P. Bureau representation for $n = 4$. *J. Knot Theory Ramifications* 27 (2018), no. 3, 1840002, 6 pp. 

s-pattern: This means a one column matrix in which the position of entries with minimum degree (in the first column of the considered matrix) are checked. For example $\begin{bmatrix} \sqrt{} \\ \circ \\ \circ \end{bmatrix}$ means that in the first column of the considered matrix there is a single entry of the smallest degree and that it is in position $(1, 1)$.

³¹[Ber-Tra.1] Beridze, A.; Traczyk, P. Bureau representation for $n = 4$. *J. Knot Theory Ramifications* 27 (2018), no. 3, 1840002, 6 pp.

s-pattern: This means a one column matrix in which the position of entries with minimum degree (in the first column of the considered matrix) are checked. For example $\begin{bmatrix} \checkmark \\ \circ \\ \circ \end{bmatrix}$ means that in the first column of the considered matrix there is a single entry of the smallest degree and that it is in position (1, 1). Altogether seven possible s-patterns exist as given below:

$$\begin{bmatrix} \circ \\ \circ \\ \checkmark \end{bmatrix}, \begin{bmatrix} \circ \\ \checkmark \\ \circ \end{bmatrix}, \begin{bmatrix} \circ \\ \checkmark \\ \checkmark \end{bmatrix}, \begin{bmatrix} \checkmark \\ \circ \\ \circ \end{bmatrix}, \begin{bmatrix} \circ \\ \circ \\ \checkmark \end{bmatrix}, \begin{bmatrix} \checkmark \\ \checkmark \\ \checkmark \end{bmatrix}$$

transformations of s -patterns — multiplication by B

Multiplication by B from the left side may affect s -patterns as illustrated in Figure:

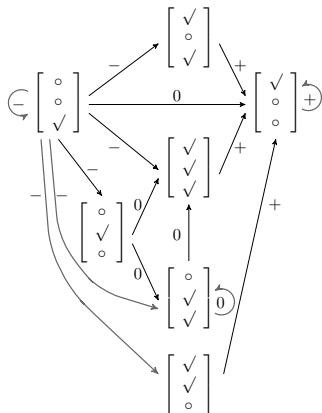


Figure 3: transformations of s -patterns — multiplication by B

transformations of s -patterns — multiplication by T

Multiplication by T may affect s -patterns as illustrated in Figure:

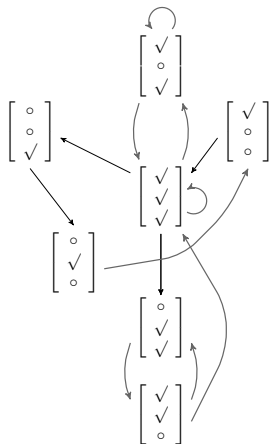


Figure 4: transformations of s -patterns — multiplication by T

Some impossible composition

Lemma

Let M be a matrix of s -pattern $\begin{bmatrix} \circ \\ \surd \\ \surd \end{bmatrix}$ or $\begin{bmatrix} \circ \\ \surd \\ \circ \end{bmatrix}$. Then the transformations corresponding to multiplication (step by step) on the left side by $BTBB$ can not be of the following form:

$$\begin{bmatrix} \circ \\ \surd \\ \surd \end{bmatrix} \xrightarrow{B} \begin{bmatrix} \circ \\ \surd \\ \surd \end{bmatrix} \xrightarrow{B} \begin{bmatrix} \surd \\ \surd \\ \surd \end{bmatrix} \xrightarrow{T} \begin{bmatrix} \circ \\ \circ \\ \surd \end{bmatrix} \xrightarrow{B} \begin{bmatrix} \circ \\ \circ \\ \surd \end{bmatrix},$$

$$\begin{bmatrix} \circ \\ \surd \\ \circ \end{bmatrix} \xrightarrow{B} \begin{bmatrix} \circ \\ \surd \\ \surd \end{bmatrix} \xrightarrow{B} \begin{bmatrix} \surd \\ \surd \\ \surd \end{bmatrix} \xrightarrow{T} \begin{bmatrix} \circ \\ \circ \\ \surd \end{bmatrix} \xrightarrow{B} \begin{bmatrix} \circ \\ \circ \\ \surd \end{bmatrix}.$$

32

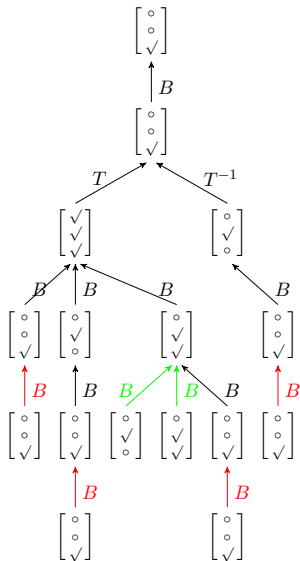
³²[Ber-Tra.1] Beridze, A.; Traczyk, P. Bureau representation for $n = 4$. *J. Knot Theory Ramifications* 27 (2018), no. 3, 1840002, 6 pp.

Main Lemma

Let ω be a word of the letters B , T and T^{-1} of the following form

$$\omega = T^{m_k} B^{n_k} \dots T^{m_2} B^{n_2} T^{m_1} B^{n_1}, \quad n_i \in \mathbb{N}, \quad m_i \in \{-1, 1\}. \quad (4)$$

If for every i we have $n_i \geq 3$, then none of transformations corresponding to any single letter in the considered word is a negative loop.



$$\omega = T^{n_{k+1}} B^{m_{k+1}-1} B T^{m_k} B^3 B^{n_k-3} \dots T^{m_2} B^{n_2} T^{m_1} B^{n_1}$$

Corollary

Let ω be a word of the form

$$\omega = T^{m_{k+1}} B^{n_k} T^{m_k} \dots T^{m_2} B^{n_2} T^{m_1} B^{n_1} \quad (5)$$

where $n_i \geq 3$ $m_i \in \{-1, 1\}$, $m_{k+1} \in -1, 0, 1, 2$. Then the change in the minimum degree of first column entries caused by multiplication by $T^i B^r$ may be:

1. a decrease (possibly by more than 1);
2. no change at all;
3. an increase by exactly 1.

Group generated by A^3 and B^3

Corollary

Let ω be a word of the form

$$\omega = T^{m_{k+1}} B^{n_k} T^{m_k} \dots T^{m_2} B^{n_2} T^{m_1} B^{n_1} \quad (5)$$

where $n_i \geq 3$, $m_i \in \{-1, 1\}$, $m_{k+1} \in -1, 0, 1, 2$. Then the change in the minimum degree of first column entries caused by multiplication by $T^i B^r$ may be:

1. a decrease (possibly by more than 1);
2. no change at all;
3. an increase by exactly 1.

Theorem

The matrices A^3 and B^3 generate a non-abelian free group of rank 2.

Thank You!